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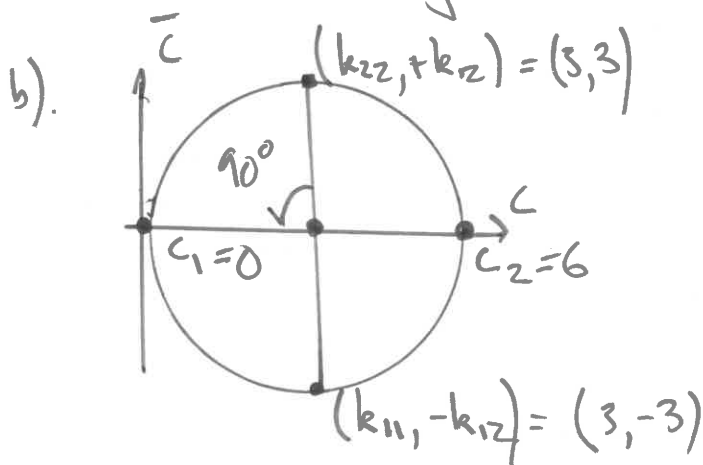
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1) a) $-3 = \frac{1}{2} k_{11} x^2 + k_{12} xy + \frac{1}{2} k_{22} y^2$

for convenience: significance $\Rightarrow$ centre of curvature lies below surface of curving

k_{11}, k_{22} : curvatures w.r.t. 1, 2 axes

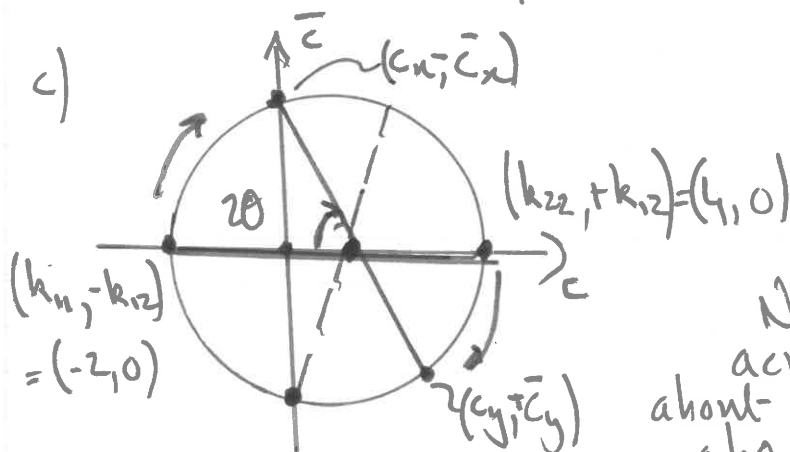
k_{12} : twisting w.r.t. 1-2 coordinate system.



$\bar{c}$ = twist: c = curvature

Since centre at $(3, 0)$
wd radius = 3
principal curvatures are $(0, 6)$

$\Rightarrow$ cylindrical, hence developable



Diameter can be rotated until first curvature is zero, as shown.

No curving along but across = straight line about which surface is also twisted: can rotate in opposite dirn by same (dashed) to give second straight line

Centre of circle at $(1, 0)$: radius = 3.

$$\bar{c}_x^2 = 3^2 - 1 \text{ (Pythagora)} \Rightarrow -\bar{c}_x = \sqrt{8} : c_y = -\sqrt{8}, c_y = 2$$

$$\Rightarrow (c_x, -\bar{c}_x) = (0, \sqrt{8}) : (c_y, +\bar{c}_y) = (2, -\sqrt{8})$$

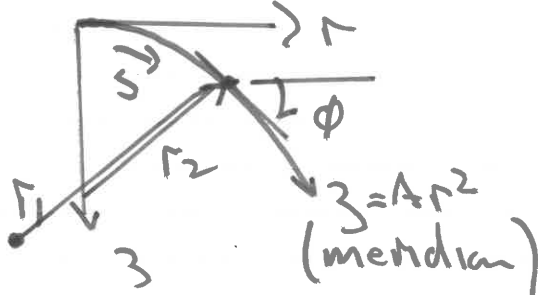
$\therefore$ twist = $\sqrt{8}$, curving across lines = 2 [units: $1/m$]

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2) a) Membrane Hypothesis: when out-of-plane loading is resisted by in-plane forces alone

b)



$z = Ar^2$: (parabolic)
 $\frac{1}{r_1} = \frac{d\phi}{ds} : \frac{1}{r_2} = \frac{1}{r} \frac{dz}{ds}$
 meridional + latitudinal curvatures (principal)

s: coordinate (intrinsic): $s_s \neq s_r$.

$$\sin \phi = dz/ds : \cos \phi = dr/ds \Rightarrow \tan \phi = dz/dr.$$

$$\therefore \tan \phi = 2Ar \Rightarrow \underline{r = \tan \phi / 2A} : \frac{dr}{d\phi} = \frac{1}{2A} \sec^2 \phi$$

$$\frac{1}{r_1} = \frac{d\phi}{ds} = \frac{d\phi}{dr} \cdot \frac{dr}{ds} = \frac{2A}{\sec^2 \phi} \cdot \cos \phi = \underline{\underline{2A \cos^3 \phi}}$$

$$\frac{1}{r_2} = \frac{1}{r} \frac{dz}{ds} = \frac{2A}{\tan \phi} \cdot \sin \phi = \underline{\underline{2A \cos \phi}}$$

With internal pressure: use eqn of cap.

$$2\pi r N_\phi \sin \phi = p \cdot \pi r^2 \Rightarrow \underline{\underline{N_\phi = pr / 2 \sin \phi}}$$

$$\Rightarrow N_\phi = \frac{1}{2 \sin \phi} \cdot \frac{\tan \phi}{2A} = \underline{\underline{p / 4A \cos \phi}}$$

$$\text{Vertical eqn} \Rightarrow N_\phi / r_1 + N_\theta / r_2 = p$$

$$\frac{1}{4A \cos \phi} \cdot 2A \cos^3 \phi + N_\theta \cdot 2A \cos \phi = p.$$

$$\Rightarrow p \cdot \cos^2 \phi / 2 + N_\theta \cdot 2A \cos \phi = p.$$

$$\underline{\underline{N_\theta = p [1 - \frac{1}{2} \cos^2 \phi] / 2A \cos \phi}}$$

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b) contd: $N_d = P/4A \cos \phi$; $N_\theta = P[1 - 1/2 \cos^2 \phi] / 2A \cos \phi$

c) For small ϕ , $\cos \phi \approx 1 \Rightarrow N_d \approx P/4A$
 $N_\theta \approx P[1 - 1/2] / 2A \approx P/4A$

$\Rightarrow N_d \approx N_\theta$ when ϕ small: BIAXIAL STRESSES

d) Relationship $N_\theta = P dA/ds$: Zick's Law.

For small ϕ $N_\theta = P/4A$ from above.

$$dA/ds = dA/d\phi \cdot d\phi/ds$$

Area enclosed $= 1/2 r_2^2 \phi = 1/2 \left(\frac{1}{2}A\right)^2 \phi \approx \phi/8A^2$
 Arc-length $\approx s = r_2 \phi \approx \phi/2A$

$$\Rightarrow dA/d\phi \approx \frac{1}{8A^2} : d\phi/ds \approx 2A$$

$$\Rightarrow dA/ds \approx \frac{1}{4A} :$$

However $N_\theta/P = \frac{1}{4A}$ via eqn $\therefore$ both equal according to Zick's Law

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①

3) General: $\omega = \frac{B}{2} [x^2 - \nu y^2] + Cxy$

a) Shape properties:

(Cartesian coordinates) $\Rightarrow K_x = -\frac{\partial^2 \omega}{\partial x^2} : K_y = -\frac{\partial^2 \omega}{\partial y^2} : K_{xy} = -\frac{\partial^2 \omega}{\partial x \partial y}$
 $\Rightarrow \underline{K_x = -B : K_y = +\nu B : K_{xy} = C(-1)}$

b) $M_x = D [K_x + \nu K_y] = D [-B + \nu^2 B] = \underline{-DB(1-\nu^2)}$
 (bending moment) $\uparrow$ $\uparrow$ flexural rigidity (M_x)

$M_y = D [K_y + \nu K_x] = D [\nu B + \nu(-B)] = 0$
 (M_y)

(twist) $M_{xy} = D [1-\nu] K_{xy} = \underline{-D[1-\nu]C}$

$\Rightarrow M_x, M_{xy}$ constant and nonzero: $M_y = \text{zero throughout}$

c) Now must consider plate equilibrium equations (in x, y coordinates).

$Q_x = \partial M_x / \partial x + \partial M_{xy} / \partial y = 0$: so is $Q_y \left[= \frac{\partial M_y}{\partial y} + \frac{\partial M_{xy}}{\partial x} \right]$

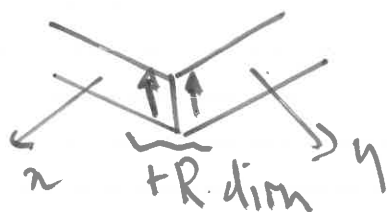
And since $\partial Q_x / \partial x + \partial Q_y / \partial y = -p$ from transverse eqn,

Then $p = 0$: no external pressure applied

Note also that Kelvin's Edge Resultant is both directions

$\bar{V}_x = Q_x + \partial M_{xy} / \partial y = 0$ (as is $\bar{V}_y$)

However corner forces $R = 2M_{xy} \neq 0 = -2D(1-\nu)C$
 do persist

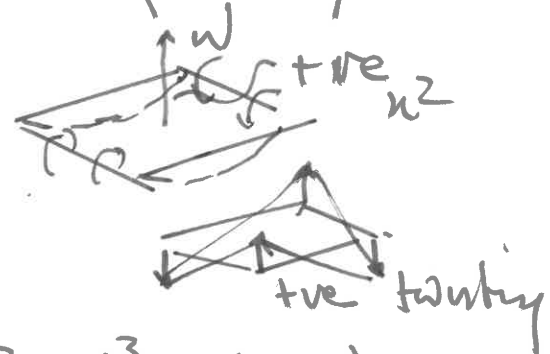
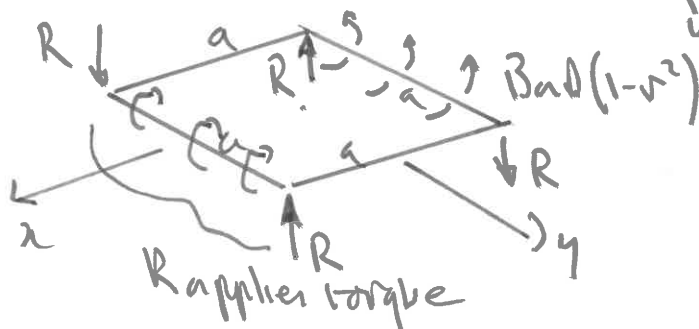


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c) contd.

There is also a moment $M = aM_n$ applied along x dirn to cause bending

$\therefore M = -BaD[1-\nu^2]$ because $M_n = \text{constant}$.
 in opposite direction to defn of M_n (and consistent with deflection.).



Given $D = Et^3/12(1-\nu^2) \Rightarrow -M = Ba \cdot \frac{Et^3}{12(1-\nu^2)} (1-\nu^2)$

$$\underline{B = -12M/Eat^3}$$

Torque from $R = aR \Rightarrow T = aR = a \cdot \frac{2D(1-\nu)C}{1}$

$\Rightarrow T = 2aD(1-\nu)C = \frac{2aEt^3}{12(1-\nu^2)}(1-\nu)C$ we have anticipated $\frac{1-\nu}{1-\nu^2}$ because

$$\Rightarrow \underline{C = 6T(1+\nu)/Eat^3}$$

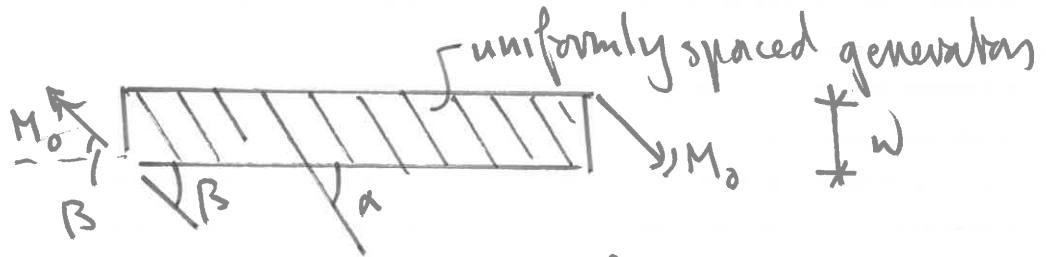
d) Gaussian curvature $= K_x K_y - K_{xy}^2 = -B^2\nu - (-C)^2$
 $= -\nu B^2 - C^2 \neq 0$

Non-zero GC $\Rightarrow$ in-plane strain from Gauss's Theorem.

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(1)

4)



a) $\frac{M_0}{B} = \leftarrow \text{Torque } M_0 \cos \beta + \uparrow \text{Bending moment } M_0 \sin \beta$

$\text{BM} / \text{Torque} = \underline{\tan \beta}$

b) (i) Generators are viable if very thin, displacements moderate and boundary conditions permit.

b) (ii) Parallel + uniform become torque and moments applied are equal + opposite.

b) (iii) If $L \gg w$, then end effects, where the pattern is not uniform are minimised.

b) (iv). Mansfield's Inext. Theory deals with non-parallel generators

b) (v) if $\beta = 90^\circ \Rightarrow$ pure bending and $\kappa = 90^\circ$ i.e. transverse generators $\equiv$ cylindrical bending along strip.

c) $M_1 = \text{total bending moment across generator.} = \underline{M_0 \cos(\beta - \alpha)}$

B.M. / unit length of generator

$M = M_1 / (w \sin \alpha) \quad [\text{constant}]$

$= M_1 \sin \alpha / w$

Curvature across $= M / D = \frac{M_1 \sin \alpha}{D w} = \underline{\underline{\frac{M_0 \cos(\beta - \alpha) \sin \alpha}{D w}}}$

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d) Strain energy = $U = \int_0^L \int_0^W \frac{1}{2} D \kappa^2 dx dy$

$\Rightarrow U = \frac{L M_0^2}{2 D W} [\cos(\beta - \alpha) \sin \alpha]^2$ ← constant w.r.t. x and $y \Rightarrow$ $\times$ LW area of strip.

$$\frac{\partial U}{\partial \alpha} = () \cdot [2 \cos(\beta - \alpha) \sin \alpha] \times [\cos \alpha \cos(\beta - \alpha) + \sin(\beta - \alpha) \sin \alpha]$$

$$\Rightarrow \frac{\partial U}{\partial \alpha} = () \cdot [\cos(\beta - \alpha) \sin \alpha \cos(2\alpha - \beta)] = 0$$

When $\cos(\beta - \alpha) = 0 \Rightarrow U = 0$;
 $\sin \alpha = 0 \Rightarrow U = 0$ } discount.

$$\Rightarrow \cos(2\alpha - \beta) = 0 \Rightarrow 2\alpha - \beta = \pm \pi/2$$

$$\Rightarrow \underline{\underline{\alpha = \pm \pi/4 + \beta/2}}$$

e) For pure torsion, $\beta = 0 \Rightarrow \alpha = \pm \pi/4$
 (twisted with respect to either sense).